

Cosmology : problem set : week 3

Solutions:

Exercise 1 : (handins !)

a) The light ray moves in the orbital plane

$$\theta = \frac{\pi}{2}, \quad \frac{d\theta}{d\lambda} = 0$$

Spelling out the line-element (3) gives

$$0 = - \left(1 - \frac{2M}{r}\right) \left(\frac{dt}{d\lambda}\right)^2 + \left(1 - \frac{2M}{r}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2$$

$$+ \underbrace{r^2 \left(\frac{d\theta}{d\lambda}\right)^2}_{=0 \text{ by choice of coordinates}} + r^2 \sin^2 \theta \left(\frac{d\phi}{d\lambda}\right)^2$$

Substituting the conserved quantities

$$e = \left(1 - \frac{2M}{r}\right) \frac{dt}{d\lambda}, \quad l = \underbrace{r^2 \sin^2 \theta}_{=1 \text{ for } \theta = \frac{\pi}{2}} \frac{d\phi}{d\lambda}$$

and the information on the orbit yields:

$$0 = - \left(1 - \frac{2M}{r}\right)^{-1} e^2 + \left(1 - \frac{2M}{r}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + \frac{1}{r^2} l^2$$

equation (4) is obtained by multiplying this relation

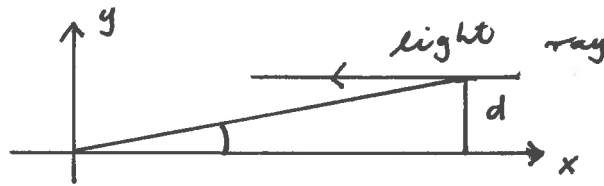
$$\text{by } \left(1 - \frac{2M}{r}\right) \cdot \frac{1}{l^2} :$$

gives

$$\frac{e^2}{e^2} = \frac{1}{e^2} \left(\frac{d\tau}{d\lambda} \right)^2 + \frac{1}{r^2} \left(1 - \frac{2M}{r} \right) \quad (1)$$

$$= w_{\text{eff.}}$$

b) Geometric analysis:



far away from the source ($r \rightarrow \infty$; $x \rightarrow \infty$) we have

$$\tan \phi = \frac{d}{x} \approx \frac{d}{r} \approx \phi$$

Thus infinitesimally

$$\frac{d\phi}{d\lambda} = - \frac{d}{r^2} \frac{dr}{d\lambda}$$

Evaluate the line element in the limit $r \rightarrow \infty$

$$0 = - \left(1 - \frac{2M}{r} \right) \left(\frac{dt}{d\lambda} \right)^2 + \left(1 - \frac{2M}{r} \right)^{-1} \left(\frac{dr}{d\lambda} \right)^2 + r^2 \left(\frac{d\phi}{d\lambda} \right)^2$$

$$= - \left(1 - \frac{2M}{r} \right) \left(\frac{dt}{d\lambda} \right)^2 + \left(1 - \frac{2M}{r} \right)^{-1} \left(\frac{dr}{d\lambda} \right)^2 + \frac{d^2}{r^2} \left(\frac{dr}{d\lambda} \right)^2$$

lim $r \rightarrow \infty$

$$0 = - \left(\frac{dt}{d\lambda} \right)^2 + \left(\frac{dr}{d\lambda} \right)^2$$

Pick the new curve parameter t :

$$0 = -1 + \left(\frac{dr}{dt} \right)^2$$

\Rightarrow

$$\frac{dr}{dt} = \pm 1 \tag{2}$$

fix sign:

r decreases as t increases (ingoing light ray):

to reflect this, the "-" sign in the relation above must be chosen:

$$\frac{dr}{dt} = -1 \tag{3}$$

Then use the geometric identity and take $\lambda = \lambda(t)$

$$\begin{aligned} \frac{d\phi}{dt} &= - \frac{d}{r^2} \underbrace{\frac{dr}{d\lambda} \frac{d\lambda}{dt}} \\ &= -1 \end{aligned}$$

Thus

$$\frac{d\phi}{dt} = \frac{d}{r^2} \tag{4}$$

Since e, l are conserved quantities, they do not change along the world line.

we then have

$$\begin{aligned}
 b &= \lim_{\tau \rightarrow \infty} \left| \frac{l}{c} \right| = \tau^2 \frac{d\phi}{d\lambda} \\
 &= \lim_{\tau \rightarrow \infty} \frac{\tau^2 \frac{d\phi}{d\lambda}}{\left(1 - \frac{2M}{\tau}\right) \frac{dt}{d\lambda}} = \tau^2 \frac{d\phi}{d\lambda} \frac{d\lambda}{dt}
 \end{aligned}$$

$$\begin{aligned}
 (4) \\
 &= d
 \end{aligned}$$

c) Use the chain rule to write:

$$\frac{d\tau}{d\lambda} = \frac{d\tau}{d\phi} \frac{d\phi}{d\lambda} = \frac{d\tau}{d\phi} \cdot \frac{l}{\tau^2}$$

Substitute into eq. 1:

$$\frac{1}{b^2} = \frac{1}{l^2} \cdot \frac{l^2}{\tau^4} \left(\frac{d\tau}{d\phi} \right)^2 + w_{\text{eff}}$$

$$\left(\frac{d\tau}{d\phi} \right)^2 = \tau^4 \left(\frac{1}{b^2} - w_{\text{eff}} \right)$$

$$\frac{d\phi}{d\tau} = \pm \frac{1}{\tau^2} \left(\frac{1}{b^2} - w_{\text{eff}} \right)^{-1/2}$$

note: at the turning point r_1 , the light ray has been bent by the angle $\Delta\phi/2$. Since the problem is symmetric around r_1 (ingoing - outgoing light ray) the full deflection angle is found as:

$$\Delta\phi = 2 \int_{r_1}^{\infty} \frac{dr}{r^2} \left[\frac{1}{b^2} - W_{\text{eff}}(r) \right]^{-1/2} \quad (5)$$

where r_1 corresponds to $\frac{d\phi}{dr} = 0$

d) Change of integration variable:

$$w = \frac{b}{r}, \quad dw = -\frac{b}{r^2} dr$$

$$W_{\text{eff}}(w) = \frac{1}{b^2} w^2 \left(1 - \frac{2M}{b} w \right)$$

$$r \rightarrow \infty, \quad w = 0; \quad r_1 \rightarrow w_1$$

Substitute into (5):

$$\begin{aligned} \Delta\phi &= 2 \int_{w_1}^0 \left(-\frac{dw}{b} \right) \cdot b \left[1 - w^2 \left(1 - \frac{2M}{b} w \right) \right]^{-1/2} \\ &= 2 \int_0^{w_1} dw \left[1 - w^2 \left(1 - \frac{2M}{b} w \right) \right]^{-1/2} \end{aligned}$$

c) Expansion

We write the denominator:

$$\left(1 - w^2 \left(1 - \frac{2M}{b} w \right) \right)^{-1/2}$$

$$= \left(1 - \frac{2M}{b} w \right)^{-1/2} \left(\left(1 - \frac{2M}{b} w \right)^{-1} - w^2 \right)^{-1/2}$$

$$\approx \left(1 + \frac{M}{b} w \right) \left(1 + \frac{2M}{b} w - w^2 \right)^{-1/2}$$

Thus the approximate integral is

$$\Delta\phi \approx \int_0^{w_+} dw \frac{\left(1 + \frac{M}{b} w \right)}{\left(1 + \frac{2M}{b} w - w^2 \right)^{1/2}}$$

f) The integral above is tabulated (see e.g. Teubner)

To determine the analytic branch of the solution

set

$$Q = ax^2 + \tilde{b}x + c$$

$$D = 4ac - \tilde{b}^2$$

$$d = \frac{4a}{D}$$

The analytic branch of the solution is determined by the sign of the determinant:

$$D = -4 - \tilde{b}^2 < 0$$

In this case

$$\int \frac{dx}{\sqrt{a}} = -\frac{1}{\sqrt{-a}} \arcsin \frac{2ax + \tilde{b}}{\sqrt{-D}} \quad \begin{array}{l} a < 0 \\ D < 0 \end{array}$$

und

$$\int \frac{x dx}{\sqrt{a}} = \frac{\sqrt{a}}{a} - \frac{\tilde{b}}{2a} \int \frac{dx}{\sqrt{a}}$$

Evaluate the integral:

$$\begin{aligned} \Delta \phi &= 2 \left[\int \frac{dx}{\sqrt{a}} + \frac{\tilde{b}}{2} \int \frac{x dx}{\sqrt{a}} \right] \\ &= 2 \left[\int \frac{dx}{\sqrt{a}} + \frac{\tilde{b}}{2} \frac{\sqrt{a}}{a} - \frac{\tilde{b}^2}{4a} \int \frac{dx}{\sqrt{a}} \right] \end{aligned}$$

substitute explicit expressions:

$$\begin{aligned} &= 2 \left(-\frac{M}{b} \sqrt{a} \Big|_0^{w_+} \right) + 2 \left(1 + \frac{M^2}{b^2} \right) \int \frac{dx}{\sqrt{a}} \\ &= \frac{2M}{b} + 2 \left(1 + \frac{M^2}{b^2} \right) (-1) \arcsin \frac{2 \frac{M}{b} - x}{\sqrt{4 + \frac{4M^2}{b^2}}} \Big|_0^{w_+} \\ &= \frac{2M}{b} - 2 \left(1 + \frac{M^2}{b^2} \right) \left[\underbrace{\arcsin(-1)}_{=-\frac{\pi}{2}} - \underbrace{\arcsin \frac{M/b}{\sqrt{1 + M^2/b^2}}}_{=\frac{M}{b} + \dots} \right] \\ &= \pi + \frac{4M}{b} + O\left(\frac{M}{b}\right)^2 \end{aligned}$$

using the definition of the deflection angle:

$$\delta\phi = \Delta\phi - \pi$$

$$= \frac{4M}{b}$$

□

Exercise 2:

a) The geodesic equation for the particle following the world line $x^\alpha(\lambda)$ is

$$\frac{d^2 x^\alpha}{d\lambda^2} = -\Gamma^\alpha_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}$$

For the t -component ($\alpha=0$) there is only one non-zero Christoffel symbol contributing

$$\Gamma^t_{tr} = \left(\frac{M}{r^2}\right) \left(1 - \frac{2M}{r}\right)^{-1}$$

Taking into account the symmetry $\Gamma^t_{tr} = \Gamma^t_{rt}$ the geodesic equation yields

$$\begin{aligned} \frac{d^2 t}{d\lambda^2} &= - \left(\Gamma^t_{tr} \frac{dr}{d\lambda} \frac{dt}{d\lambda} + \Gamma^t_{rt} \frac{dt}{d\lambda} \frac{dr}{d\lambda} \right) \\ &= - 2 \left(\frac{M}{r^2} \right) \left(1 - \frac{2M}{r} \right)^{-1} \frac{dr}{d\lambda} \frac{dt}{d\lambda} \end{aligned}$$

b) Take the λ -derivative of the conserved quantity e :

$$\begin{aligned} \frac{de}{d\lambda} &= \left(1 - \frac{2M}{r} \right) \frac{d^2 t}{d\lambda^2} + \left(\frac{2M}{r^2} \right) \frac{dr}{d\lambda} \frac{dt}{d\lambda} \\ &= \left(1 - \frac{2M}{r} \right) \left(\frac{d^2 t}{d\lambda^2} + \left(1 - \frac{2M}{r} \right)^{-1} \frac{2M}{r^2} \frac{dr}{d\lambda} \frac{dt}{d\lambda} \right) \end{aligned}$$

- the second bracket is precisely the geodesic equation
- thus e is constant along the world line.